

Features

- Two channel quadrature output
- Bushing or servo mount
- Square wave signal
- Small size
- Resolution to 256 PPR
- CMOS and TTL compatible
- Long life

- Ball bearing option for high operating speed up to 3000 rpm
- RoHS compliant*

EN - Rotary Optical Encoder

General Information

The Bourns® EN model is a self-contained rotary optical encoder. It produces a 2-bit quadrature signal which is suitable for digital systems where both magnitude and direction of adjustment must be provided. The EN encoder is ideal for use as a digital panel control or as a position sensing device in applications where long life, reliability, high resolution and precise linearity are critical.

The EN series encoder converts rotary input into electrical signals which can be used by microprocessors without A/D conversion.

Bourns encoder output signals are square wave digital pulses which do not require debounce circuitry. Both features make it possible to significantly reduce the memory overhead, wiring and wiring interconnects required by other types of control devices.

EN optical encoders offer a useful rotational life of from 10 million to 200 million shaft revolutions, making them ideal for extended service applications. The Bourns encoder is also compact and well suited for situations where the available space is limited.

Additional Information

Click these links for more information:











PRODUCT TECHNICAL INVENTORY SAMPLES CONT SELECTOR LIBRARY

Electrical Characteristics	
Output	2-bit quadrature code, Channel A leads Channel B by 90 ° (electrical) with clockwise rotation
Insulation Resistance (500 VDC)	1,000 megohms
	Continuous
Supply Voltage	
Supply Current	26 mA maximum
Output Voltage	
Low Output	
High Output	4 V minimum
Output Current	
	25 mA minimum
Rise/Fall Time	
Shaft RPM (Ball Bearing)	
Power Consumption	
	180 ° ±45 ° typ.
Phase (Electrical Degrees, Channel A to Channel B)	
Environmental Characteristics	
Operating Temperature Range	-40 °C to +75 °C (-40 °F to +167 °F)
	40 °C to +85 °C (-40 °F to +185 °F)
Vibration	5 G
Shock	50 G
Rotational Life	
A & C Bushings (300 rpm maximum)**	
W, S & T Bushings (3,000 rpm maximum)**	
IP Bating	IP 40

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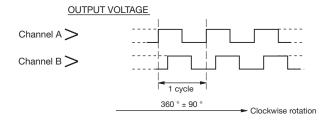


**For resolutions ≤ 128 quadrature cycles per shaft revolution.

EN – Rotary Optical Encoder

Mechanical Characteristics	
Mechanical Angle	
Torque (Starting and Running)	
A & C Bushings (Spring Loaded for Optimum Feel)	
W, S & T Bushings (Ball Bearing Shaft Support)	
Mounting Torque	
Shaft End Play	
Shaft Radial Play	
Weight	
Terminals	
Soldering Condition	
Manual Soldering	96.5Sn/3.0Ag/0.5Cu solid wire or no-clean rosin cored wire
•	370 °C (700 °F) max. for 3 seconds
Wave Soldering	96.5Sn/3.0Ag/0.5Cu solder with no-clean flux
•	260 °C (500 °F) max. for 5 seconds
Wash processes	Not recommended
Marking	Manufacturer's trademark, name, part number, and date code.
Hardware One lock	washer and one mounting nut supplied with each encoder, except on servo mount versions.

Quadrature Output Table



STANDARD RESOLUTIONS AVAILABLE

(Full quadrature output cycles per shaft revolution)

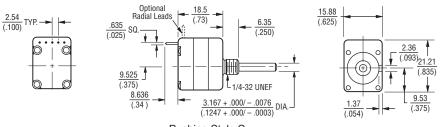
25* 125 50* 128 64 200 256

For Non-Standard Resolutions—Consult Factory

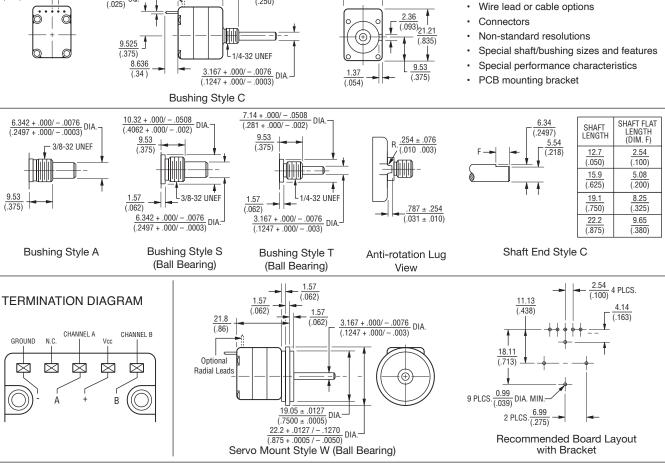
* Channel B leads Channel A

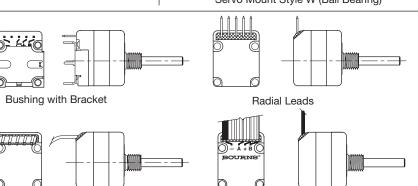
EN – Rotary Optical Encoder

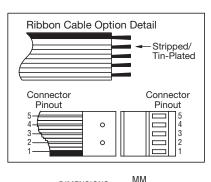
Dimensional Drawings



Consult factory for options not shown, including:





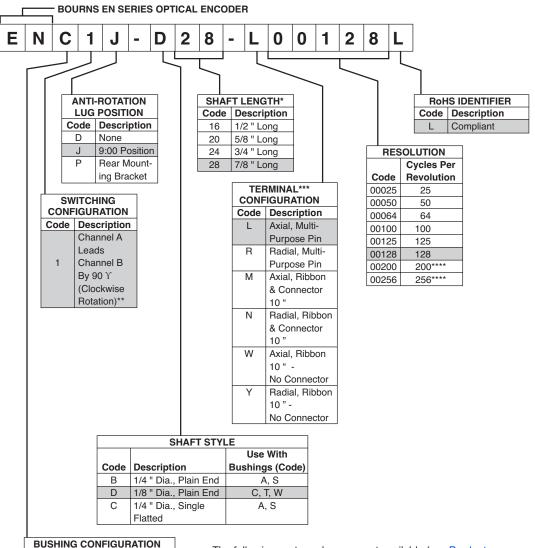


MM DIMENSIONS: (INCHES)

Axial Ribbon Cable Option

Radial Ribbon Cable Option

How To Order



Code Description 3/8 "D X 3/8 "L Threaded С 1/4 "D X 1/4 "L Threaded S 3/8 "D X 3/8 "L Threaded (Ball Bearing) 1/4 "D X 3/8 "L Threaded

(Ball Bearing) W Servo Mount 7/8 "D (Ball Bearing) -Not available with Anti-Rotation Lug option

The following part numbers are not available (see Product Obsolescence Memo):

ENA2J-B28-L00064L ENA2J-B28-L00100L ENA2J-C28-L00128L

- Shaft length measured from mounting surface.
- 25 and 50 PPR is reversed (Channel B leads Channel A). Standard ribbon cable is 10 " long. Consult factory for other lengths.
- **** Available with S, T, and W bushing configuration only.

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